## Local density

### Definition and basic properties

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## Definition of local density

Local density has been introduced by Mandallaz [1991, section 3.1 starting on page 18]. A key property of local density is defined by

$$\int_D Y(x)dx = Y. \tag{1}$$

The definite integral of local density Y(x) in domain  $D \subset \mathbb{R}^2$  (geographical area) equals the total amount of variable Y in D.

Expected value of local density equals the mean value of Y in D

$$\mathbb{E}[Y(x)] = \frac{1}{\lambda(D)} \int_D Y(x) dx = \bar{Y}, \tag{2}$$

where  $\lambda(D)$  stands for the total area of D.



# The utility of local density I

#### **Naturalness**

Parameter estimation proceeds by **continuous-population** approach avoiding imperfections of finite population methodology when applied to NFIs.

- study area D can't be tessellated into congruent units (population elements) of circular (or any other) shape of sample plots<sup>a</sup>
- unknown size of some populations e. g. trees.
- fuzziness of the definition of population's elements<sup>b</sup> e. g. dead wood, streams, roads . . .



<sup>&</sup>lt;sup>a</sup>Sample plots are not population's elements!

<sup>&</sup>lt;sup>b</sup>Field work complications.

## The utility of local density II

### Simplicity of estimation procedures

After the introduction of local density, all parameters can be estimated using an unified approach - **the Horwitz-Thompson theorem for continuous populations** [Cordy, 1993].

### Flexibility

Sampling design and protocols can be defined in such a way that for any variable we can evaluate local density anywhere in D.





# Point sampling

In the very typical and simplest case, point sampling is used to estimate the extent of arbitrarily defined subregions  $^1$  within the survey area or geographical domain D.

Local density is defined as an **indicator variable** expressing a membership of inventory (sample) point x to particular land-category K

$$I_{K}(x) = \begin{cases} 1 & \text{if } x \in K \\ 0 & \text{if } x \notin K. \end{cases}$$
 (3)



<sup>&</sup>lt;sup>1</sup>For example the total area of a land-use category.

## Selection of stems on circular plots I

Following description was borrowed from Mandallaz [2007, section 4.2 starting on page 55].

Let's define **concentric circles**  $K_r$  (one, usually two or three) on each inventory (sample) point.

Stem i is selected if and only if it is located inside a circle  $K_r(x) = \{y \in \mathbb{R}^2 \mid d(x,y) \leq r\}$  with radius r and center point coincident with the inventory point x.

The notation d(x,y) is used for Euclidean distance between x and y (an arbitrary point within the circle). Position of a stem is given by orthogonal projection of a point lying on the central axis in breast height (1.3 m) into the 2D plane of the coordinate system in use.

## Selection of stems on circular plots II

Now let's define an indicator variable  $I_i(x)$  for stem i and inventory point x as

$$I_i(x) = \begin{cases} 1 & \text{if } u_i \in K_r(x) \\ 0 & \text{if } u_i \notin K_r(x). \end{cases}$$
 (4)

Furthermore define N circles  $K_i(r) = K_r(u_i)$  with constant radius r and center points  $u_i$  coincident with stem positions. Stem i gets selected if an only if any of the inventory points x is falls into circle  $K_i(r)$ :

$$I_i(x) = 1 \Leftrightarrow x \in K_i(r). \tag{5}$$

The circle  $K_i(r)$  is called **inclusion zone** of the stem i. To each stem i we assign an inclusion zone the size of which in the most typical case depends on particular stem's attributes (dbh, height, species etc.).



## Selection of stems on circular plots III

### Definition of local density, sampling protocol for stems

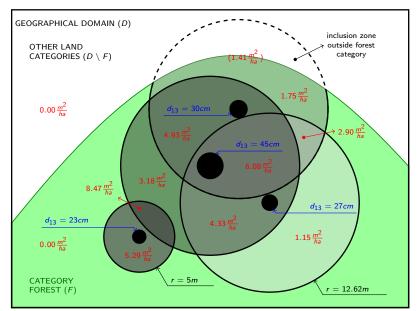
Local density function corresponding to above described sampling protocol is given by

$$Y(x) = \sum_{i \in \mathcal{P}} \frac{I_i(x)Y_i}{\lambda(K_i \cap F \cap A)}.$$
 (6)

- $\lambda(K_i)$  is the size of the circular segment  $K_i$  for stem i
- ullet  $\mathcal P$  is a finite population of stems located on accessible areas A within geographical domain D and within forest landuse-category F
- ullet  $Y_i$  is the observed quantity on stem i we want to estimate in D
- Y(x) follows (1) and (2)
- $\lambda(K_i \cap F \cap A)$  is the common area of regions  $K_i$ , F and A

Definition 6 supposes that plots with center point outside forest or inside inaccessible area are never established. The area in the denominator compensates for the edge-effect, which would otherwise occur.

## Local density, selection of stems, CZNFI2



## Modifications of local density I

### Relascope (or Bitterlich) sampling

- also known as the angle count technique
- highly effective sampling protocol for stems
- see Mandallaz [2007, section 4.2 starting on page 57] and Gregoire and Valentine [2008, section 8 starting on page 247] for details

### Line intersect sampling

- very common extensions are various protocols using transects<sup>a</sup>
- original reference is Kaiser [1983]
- see Gregoire and Valentine [2008, section 9 starting on page 270] for a thorough and useful introduction

<sup>&</sup>lt;sup>a</sup>Estimating total length of linear objects, total area of aerial objects, total volume of 3D objects e. g. lying dead wood.

## Modifications of local density II

### Generalized local density

- local density modified for two-stage selection procedure at the sample plot level
- some stem-specific variables (e. g. height and upper diameter)
  are measured on a subset of stems registered on the plot
- see Mandallaz [2007, section 4.4 starting on page 69]

### Tract sampling - reduction of travel cost

- tracts are defined by a fixed number of **translation vectors**
- each of these vectors defines position of one inventory plot which altogether form a tract (e. g. plots organized in a square tract)
- see Mandallaz [2007, section 4.3 starting on page 65] and Gregoire and Valentine [2008, section 7 starting on page 207]

# Modifications of local density III

### Edge effect corrections

- for specific sampling protocols an edge effect occurs
- it leads to underestimation of the amount of resource in D
- in most cases the definition of local density has to be adjusted to compensate for the edge effect
- see Mandallaz [2007, section 4.2 starting on page 52] and Gregoire and Valentine [2008, section 7.5 starting on page 223] for a complete treatment of the topic



### Literature

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